Solomon Practice Paper Pure Mathematics 6E

Time allowed: 90 minutes

Centre: www.CasperYC.club
Name:

## Teacher:

| Question | Points | Score |
| :---: | :---: | :---: |
| 1 | 5 |  |
| 2 | 6 |  |
| 3 | 6 |  |
| 4 | 8 |  |
| 5 | 11 |  |
| 6 | 13 |  |
| 7 | 13 |  |
| 8 | 13 |  |
| Total: | 75 |  |

How I can achieve better:

1. The point $P$ represents a variable point $z=x+\mathbf{i} y$ in an Argand diagram where $x, y \in \mathbb{R}$.

Given that the locus of $P$ is a circle with centre $-1+\mathbf{i}$ and radius 2 , find
(a) an equation of the circle in terms of $z$,
(b) the points on the locus of $P$ which represent real numbers.
2. Prove by induction that $2^{n}>2 n$ for all integers $n, n \geq 3$.
3. (a) By using the series expansion for $\ln (1+2 x)$ and the series expansion for $\mathrm{e}^{x}$, or otherwise, and given that $x$ is small, show that

$$
\ln (1+2 x)-2 x \mathrm{e}^{-x} \approx A x^{3},
$$

and find the value of $A$.
(b) Hence find

$$
\lim _{x \rightarrow 0}\left(\frac{\ln (1+2 x)-2 x \mathrm{e}^{-x}}{x^{3}}\right) .
$$

4. 

$$
\mathbf{A}=\left(\begin{array}{ccc}
2 & -1 & 1 \\
0 & 1 & -1 \\
-3 & 3 & 1
\end{array}\right)
$$

(a) Show that $\left(\begin{array}{l}1 \\ 1 \\ 0\end{array}\right)$ is an eigenvector of $\mathbf{A}$ and find the corresponding eigenvalue.
(b) Prove that A has only one real eigenvalue, showing your working clearly.
5. A transformation $T$ from the $z$-plane to the $w$-plane is defined by

$$
w=z^{2}
$$

where $z=x+\mathbf{i} y, w=u+\mathbf{i} v$ and $x, y, u$ and $v$ are real.
(a) Show that $T$ transforms the $\operatorname{line} \operatorname{Im}(z)=2$ in the $z$-plane onto a parabola in the $w$-plane and find an equation of the parabola, giving your answer in terms of $u$ and $v$.

The image in the $w$-plane of the half-line $\arg (z)=\frac{\pi}{4}$ is the half-line $l$.
(b) Find an equation of $l$.

The parabola and the half-line in the $w$-plane are represented on the same Argand diagram. Their point of intersection is represented by $P$.
(c) Find the complex number which is represented by $P$, giving your answer in the form $a+\mathbf{i} b$ where $a$ and $b$ are real.
6. It is given that $y$ satisfies the differential equation

$$
\frac{\mathrm{d} y}{\mathrm{~d} x}=x^{2}+y \cos (x) \quad \text { and } \quad y=1 \quad \text { at } \quad x=0 .
$$

(a) i. Use the differential equation to find expressions for $\frac{\mathrm{d}^{2} y}{\mathrm{~d} x^{2}}$ and $\frac{\mathrm{d}^{3} y}{\mathrm{~d} x^{3}}$.
ii. Hence, or otherwise, find $y$ as a series in ascending powers of $x$ up to and including the term in $x^{3}$.
iii. Use your series to estimate the value of $y$ at $x=-0.1$.
(b) Use the approximation $\left(\frac{\mathrm{d} y}{\mathrm{~d} x}\right)_{0} \approx \frac{y_{1}-y_{-1}}{2 h}$ to estimate the value of $y$ at $x=0.1$.
7. Referred to an origin $O$, the points $A, B, C$ and $D$ have coordinates $(1,1,0),(3,2,5),(0,-1,-4)$ and $(-2,-5,0)$ respectively.
(a) Find, in the form $\mathbf{r} . \mathbf{n}=p$, an equation of the plane $\Pi$ passing through $A, B$ and $C$.

The line $l$ passes through $D$ and is perpendicular to $\Pi$.
(b) Find a vector equation of $l$.

The line $l$ meets the plane $\Pi$ at the point $E$.
(c) Find the coordinates of $E$.

The point $F$ is the reflection of $D$ in $\Pi$.
(d) Find the coordinates of $F$.
8. The transformation $T: \mathbb{R}^{3} \mapsto \mathbb{R}^{3}$ is represented by the matrix $\mathbf{M}$ where

$$
\mathbf{M}=\left(\begin{array}{ccc}
2 & 1 & -1 \\
0 & 3 & 1 \\
2 & 2 & 0
\end{array}\right)
$$

(a) Find $\mathbf{M}^{-1}$, showing your working clearly.
(b) Find the Cartesian equations of the line mapped by the transformation $T$ onto the line with equations

$$
\frac{x-1}{3}=\frac{y+1}{-3}=\frac{z}{4} .
$$

